



Austrian Light Vehicle Proving Region for Automated Driving

The comprehensive Test- and Innovation Lab to test all levels of automated driving functions!

This project is supported by:

 Federal Ministry
Republic of Austria
Transport, Innovation
and Technology

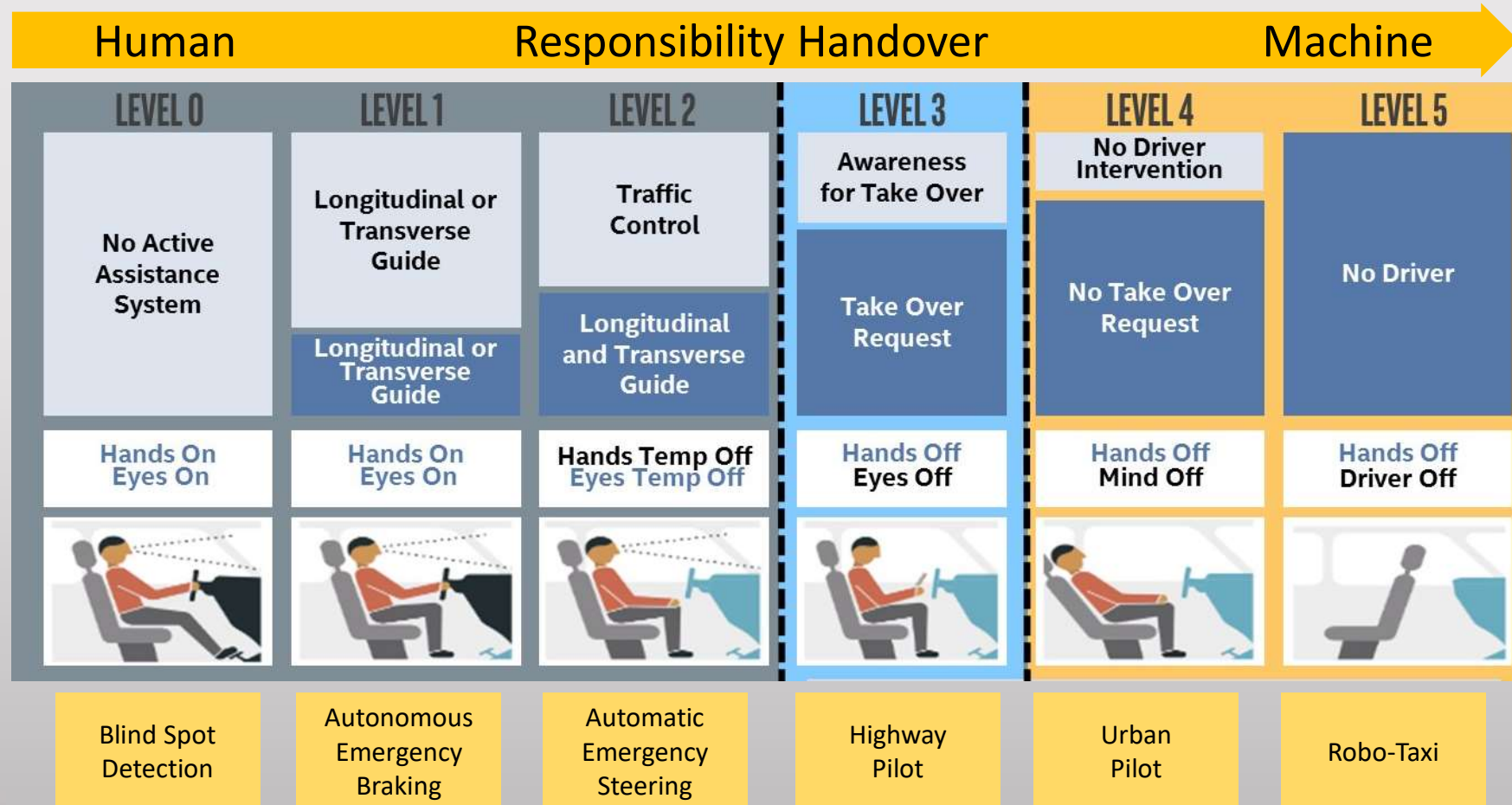


Deutsches Zentrum
für Luft- und Raumfahrt



BOSCH
Invented for life

Society of Automotive Engineers (SAE) defined six Automation Levels



Why ALP.Lab?

Comprehensive Test & Innovation Lab to test all levels of automated driving functions



How to make a self-driving vehicle safe

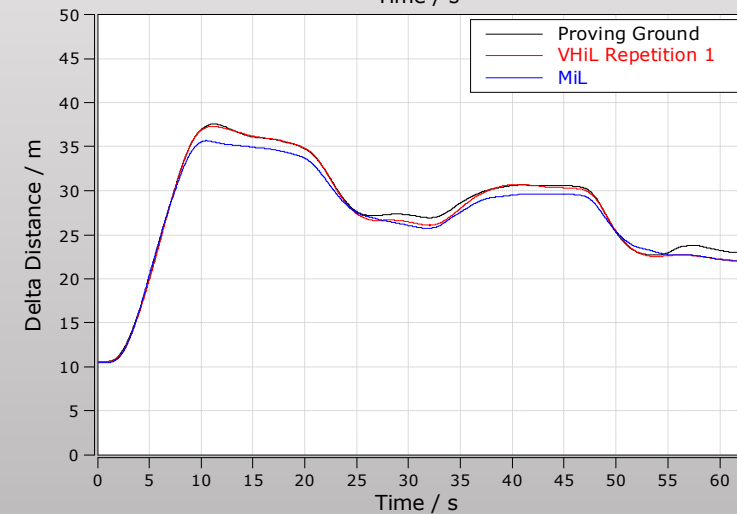
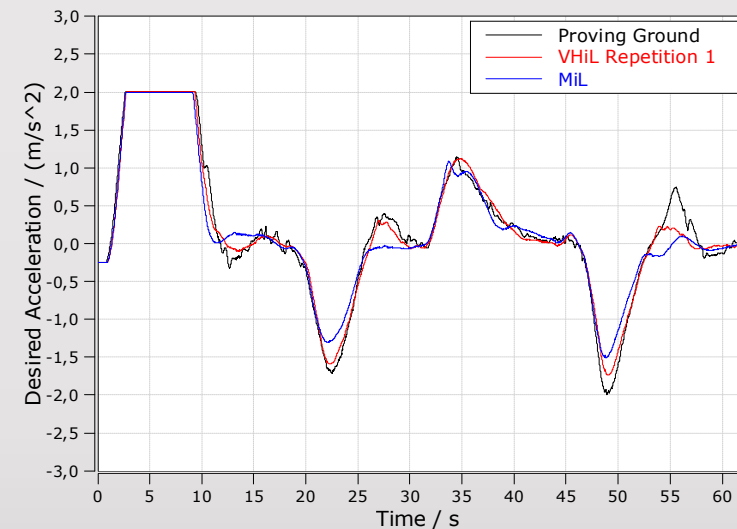
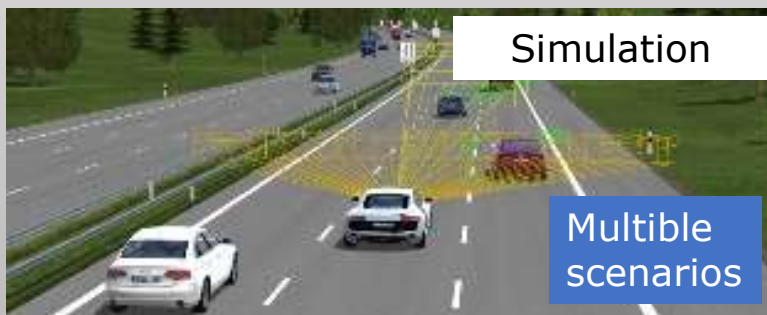
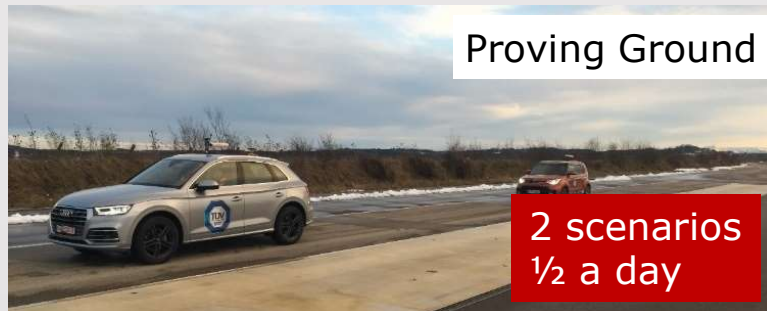
Self-driving vehicles may have to drive up to 11 billion miles (**17.7 billion km**) before we can have reliable statistics on their safety to compare to human drivers

And this is where things get complicated. There's plenty of data for us to judge the safety (or lack thereof) of vehicles driven by humans, yet there's very little that exists for autonomous vehicles, and much of what does exist is not available to the public or to regulators. Researchers at the **RAND Corporation** estimate that self-driving vehicles may have to drive up to 11 billion miles (17.7 billion km) before we can have reliable statistics on their safety to compare to human drivers, which means 11 billion miles for each autonomous-driving system. Not only will that take a long time, but we'll also have to rely on private companies for the data when they have a financial interest in making sure those statistics portray their systems in a positive light.

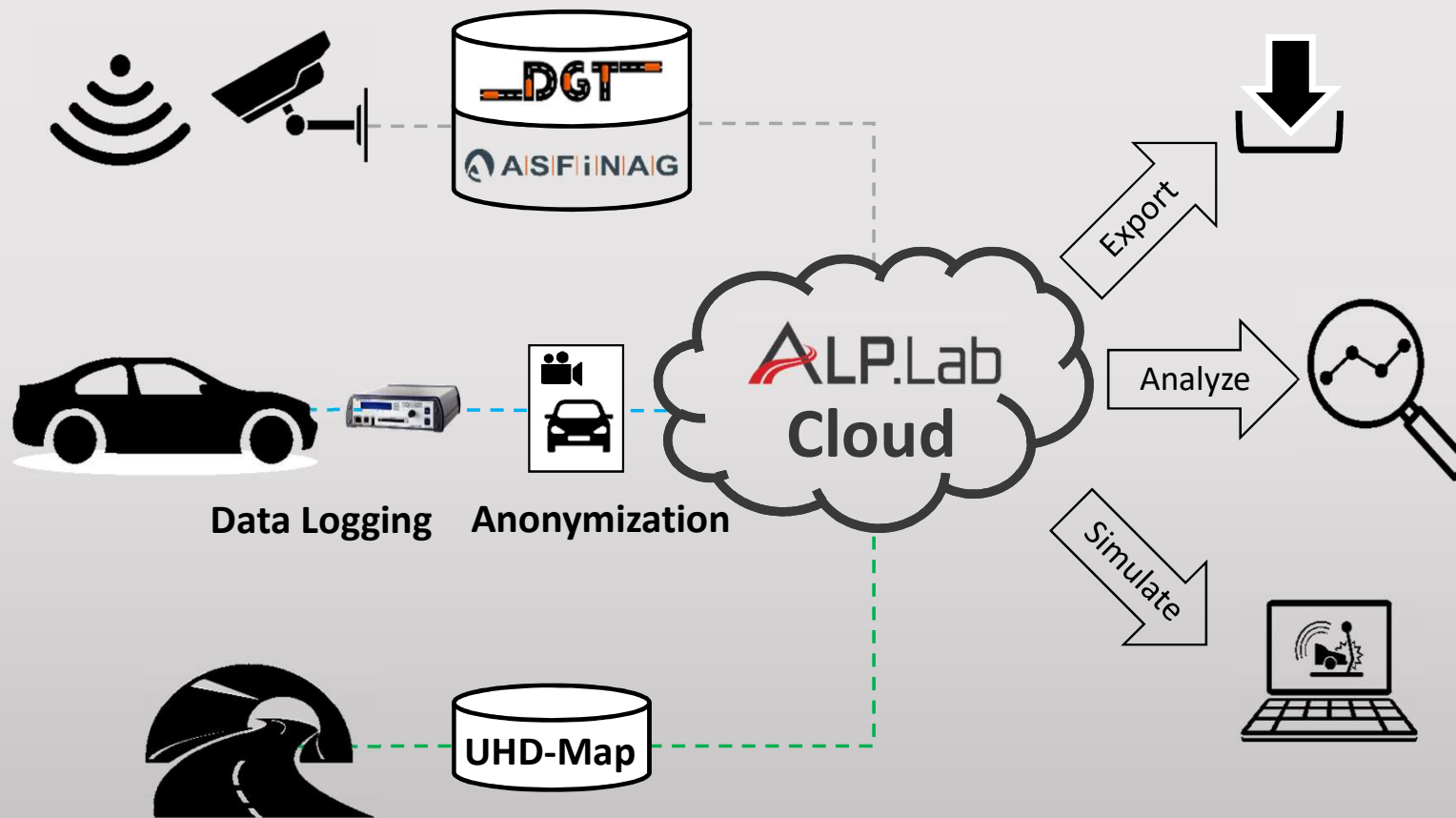
<https://medium.com/@parismarx/are-self-driving-cars-really-safer-than-human-drivers-56a72bde2f41>

Source: Rand Corporation

Testing, testing, testing ... real and virtual testing



ALP.Lab Cloud – a comprehensive Platform for Proving Ground Operators



The ALP.Lab Cloud is the gateway between the real world infrastructure, vehicles and objects and the digital representative ("digital twin") to enable end2end-testing for automated and autonomous driving functions and vehicles in a safe, real and virtual environment.

The ALP.Lab Cloud is the core component to offer data driven business models to proving ground operators including

- + public roads and private test tracks
- + logging of in vehicle data
- + ultra high definition maps.

and offers customers and partners access to aggregated and fused data of test drives and a growing number of traffic and scenario models.

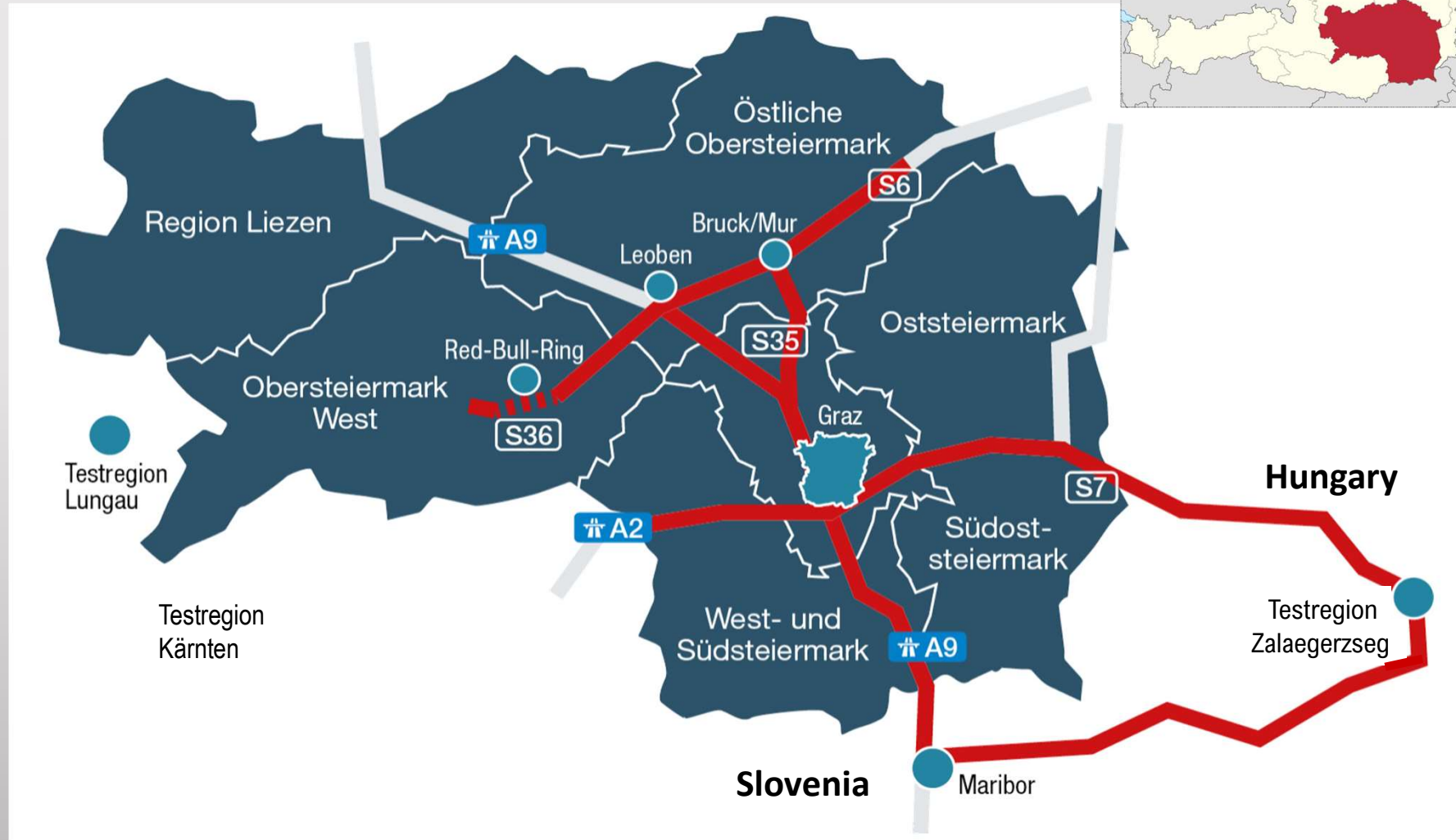
The open interfaces of the ALP.Lab Cloud enable partners and customers (OEMs, R&D institutions, road operators, etc.) to export and analyse data to simulate AD and ADAS functions at the proving ground and in private simulation environment.

Fully digital integrated Testinfrastruktur für AD (Autonomous Driving) und ADAS (Advanced Driver Assistance Systems)



- ✓ **Model/Software/Hardware in the Loop**
Bring in scenarios from road tests into virtual environment to test SW and HW functions
- ✓ **Driving Simulator**
Test the Human-Machine Interface (HMI) for ADAS/AD specific situations, e.g. hand-over from vehicle to driver
- ✓ **Vehicle in the Loop (Driving Cube™)**
Automated system evaluation of a complete vehicle in a reproducible environment on a test bed
- ✓ **Proving Ground Tests**
Individual desired scenarios and manoeuvres, e.g. EuroNCAP
- ✓ **Public Road Tests**
Test in regional specific real-world scenarios
- ✓ **Data and Cloud Services**
Data processing and management
Analysing and reporting
Simulation environment

ALP.Lab Test-Region in Styria



ALP.Lab offers a broad range of proving grounds

Proving Ground



Public Road

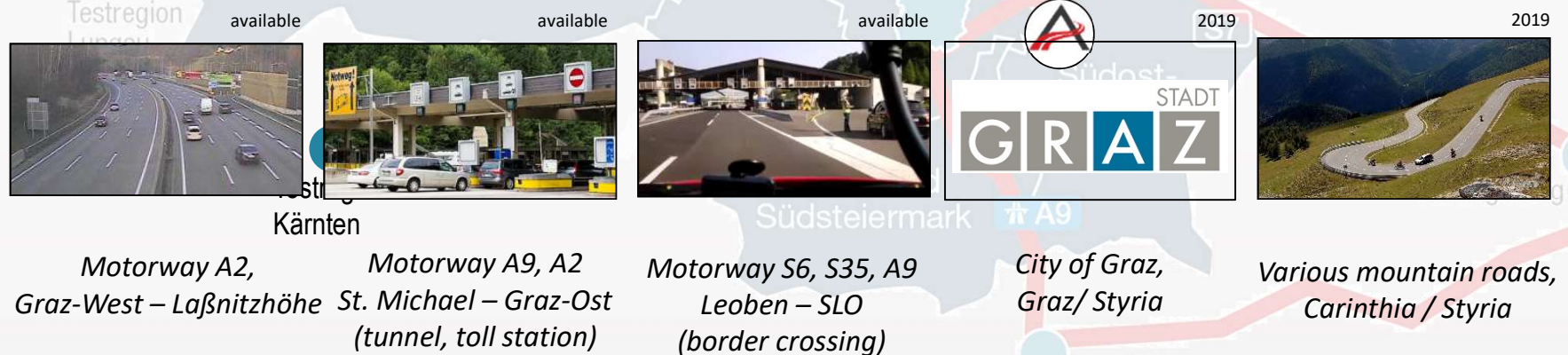




Foto: G.Greiner

UHDmaps deliver Ground Truth for Test & Validation

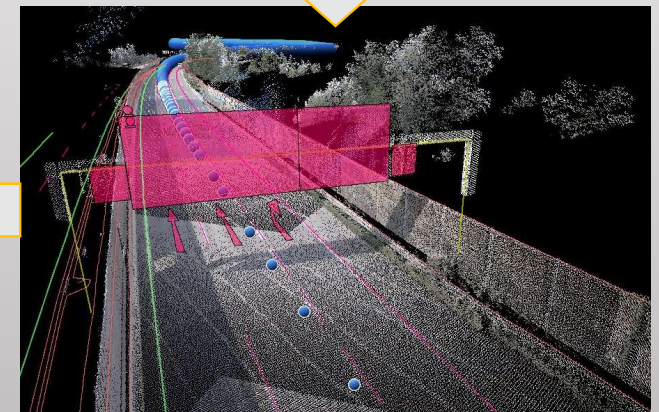
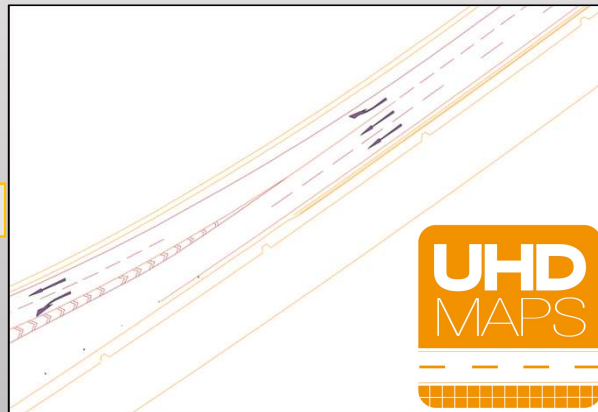


Leica Pegasus 2 Ultimate Dual Head



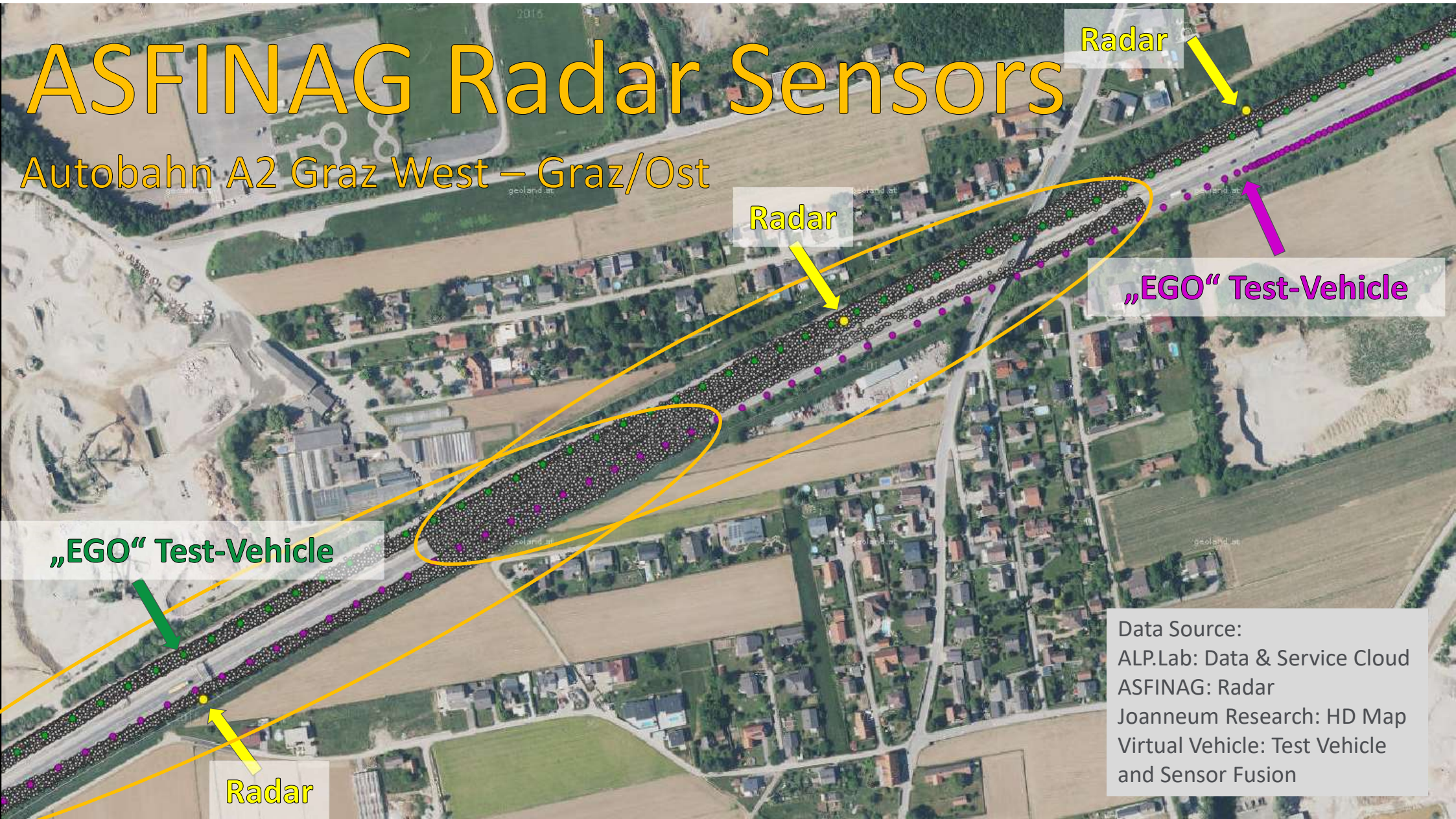
UHD Exports

- Road5
- OpenDrive
- Road2Simulation
- Cloud Service



ASFINAG Radar Sensors

Autobahn A2 Graz West – Graz/Ost



Radar

Radar

„EGO“ Test-Vehicle

„EGO“ Test-Vehicle

Radar

Data Source:
ALP.Lab: Data & Service Cloud
ASFINAG: Radar
Joanneum Research: HD Map
Virtual Vehicle: Test Vehicle
and Sensor Fusion

Extraction and Sensor Fusion

An aerial photograph of a multi-lane highway (Autobahn A2) running diagonally from the bottom left towards the top right. The highway is flanked by agricultural fields and some residential areas. Overlaid on the highway are numerous small, colored circles (red, green, purple, yellow) representing sensor data points or vehicle positions. The background shows a mix of brown and green fields, some buildings, and a road intersection on the right.

Autobahn A2 Graz West – Graz/Ost

Data Source:
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